

NONLOCAL MORPHOLOGICAL LEVELINGS BY PARTIAL DIFFERENCE EQUATIONS OVER WEIGHTED GRAPHS

Vinh-Thong Ta, Olivier Lézoray, Abderrahim Elmoataz

Université de Caen Basse-Normandie, GREYC CNRS UMR 6072, ENSICAEN, Image Team, France

1 Introduction

The two fundamental operations in Mathematical Morphology (MM) are **dilations** and **erosions**. They employ so-called *structuring elements*. Classically, such operators are performed by considering sets and lattices operations. Their implementations are usually relying on algebraic (discrete) settings.

Continuous morphology

Alternative formulations [1] based on nonlinear *partial difference equations* (PDEs) have been proposed. They show that multiscale dilations δ and erosions ε of a function $f^0: \mathbb{R}^n \rightarrow \mathbb{R}$ by a structuring element $B = \{x \in \mathbb{R}^n : \|x\|_p \leq 1\}$ can be generated by these PDEs

$$\delta(f) = \partial_t f = +\|\nabla f\|_p \quad \text{and} \quad \varepsilon(f) = \partial_t f = -\|\nabla f\|_p,$$

with $f = f^0$ at $t=0$, ∇ is the gradient operator and $\|\cdot\|_p$ is the \mathcal{L}_p -norm.

Motivations

The PDEs framework has **advantages** (better geometry approximation and subpixel accuracy) and **drawbacks** (numerical discretization is difficult for high or irregular domains and only local derivatives are considered). Moreover, MM provides well known methods for images but **there no exist general extension** for the processing of high dimensional unorganized data.

Contributions

PDEs based operations are **extended** to *nonlocal discrete schemes* by **partial difference equations (PdEs)** over graphs.

The proposed formulation has advantages. **Local and nonlocal processing** are naturally and directly enabled within a same formulation. **Any discrete domain** that can be described by a graph can be considered. These points provide **new insights** of morphological operations to unorganized data and to nonlocal image processing.

2 The ingredients

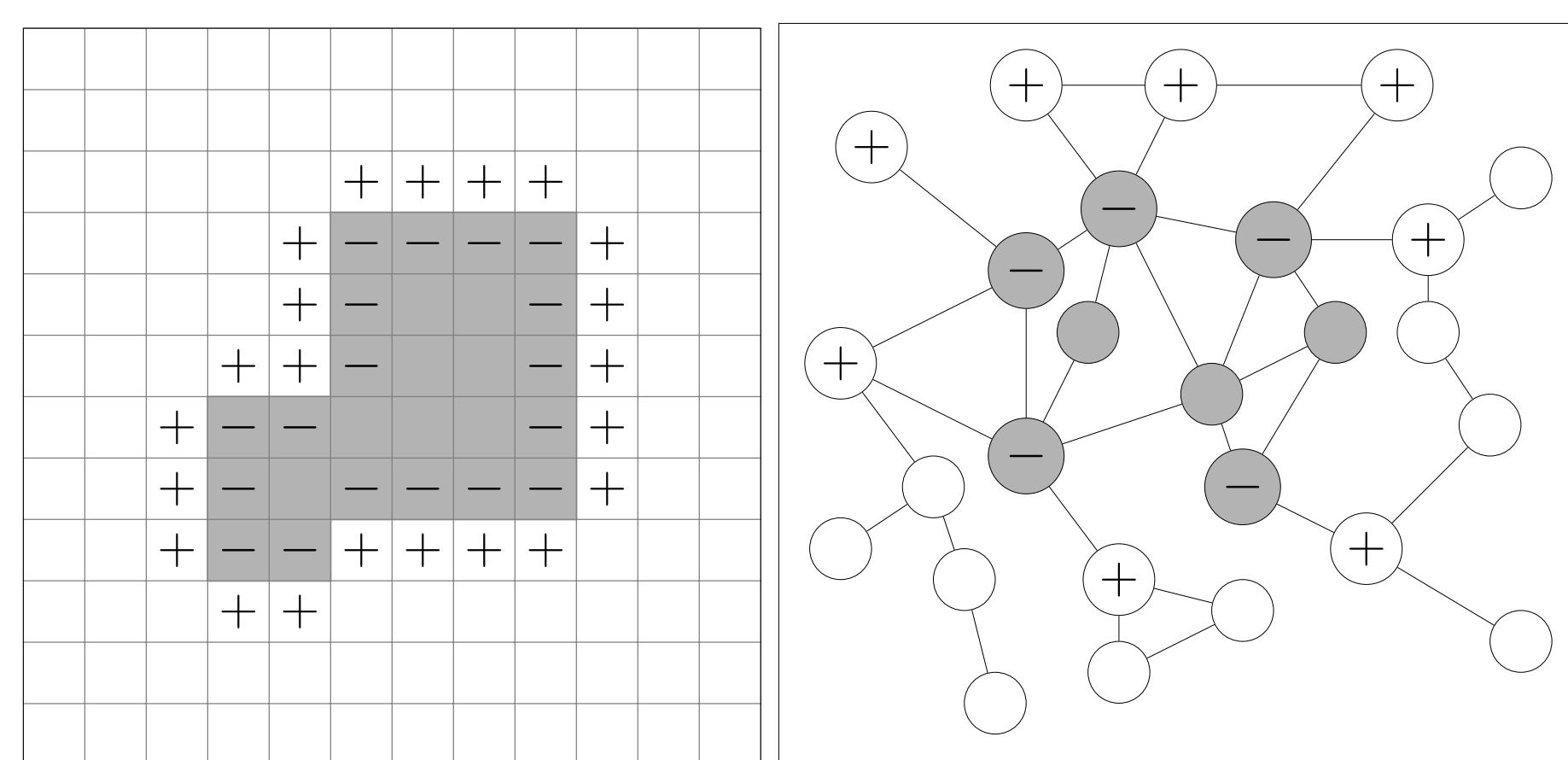
Weighted graph

A *weighted graph* $G=(V, E, w)$ is composed of a set V of *vertices*, a set $E \subset V \times V$ of *weighted edges* and a *weight function* $w: V \times V \rightarrow \mathbb{R}^+$. An *edge* uv of E connects two adjacent vertices u and v . The Hilbert space of functions defined on V is noted $\mathcal{H}(V)$.

Graph boundary sets

Let \mathcal{A} (gray vertices) be a set of connected vertices with $\mathcal{A} \subset V$ (\mathcal{A}^c is its complement) such that for all $u \in \mathcal{A}$, there exists a vertex $v \in \mathcal{A}$ with $uv \in E$. Then we define

the outer set: $\partial^+ \mathcal{A} = \{u \in \mathcal{A}^c : \exists v \in \mathcal{A} \text{ with } uv \in E\}$ and
the inner set: $\partial^- \mathcal{A} = \{u \in \mathcal{A} : \exists v \in \mathcal{A}^c \text{ with } uv \in E\}$.



(a) 4-adjacency grid graph

(b) Arbitrary graph

Discrete gradients on graphs and norms

From [2,3] works, we define **two weighted directional discrete gradients** of a function $f \in \mathcal{H}(V)$ at a vertex $u \in V$ by

$$\begin{aligned} (\nabla_w^+ f)(u) &= (\partial_v^+ f(u))_{uv \in E} = (\max(0, w_{uv}^{1/2}(f(v) - f(u))))_{uv \in E} \\ (\nabla_w^- f)(u) &= (\partial_v^- f(u))_{uv \in E} = (\min(0, w_{uv}^{1/2}(f(v) - f(u))))_{uv \in E} \end{aligned}$$

The \mathcal{L}_p -norm and \mathcal{L}_∞ -norm of $(\nabla_w^+ f)(u)$ are

$$\begin{aligned} \|(\nabla_w^+ f)(u)\|_p &= \left[\sum_{v \sim u} w_{uv}^{p/2} |\max(0, f(v) - f(u))|^p \right]^{1/p} \\ \|(\nabla_w^+ f)(u)\|_\infty &= \max_{v \sim u} \left(w_{uv}^{1/2} |\max(0, f(v) - f(u))| \right). \end{aligned}$$

Norms of $(\nabla_w^- f)(u)$ is obtained by replacing the max operator by the min operator.

3 From continuous to discrete

With the **two discrete gradients** and the **graph boundary sets**, dilation and erosion can be interpreted as

- A growth process that *adds* vertices and *maximize* a surface gain proportional to $\|\nabla_w^+ f\|_p$ (**dilation**).
- A contraction process that *removes* vertices and *minimize* a surface gain proportional $\|\nabla_w^- f\|_p$ (**erosion**).

Dilation and erosion reformulation

Then, the **reformulation** of *continuous* dilations δ and erosions ε over **any weighted graph** is

$$\begin{aligned} \delta(f(u)) &= \partial_t f(u) = +\|(\nabla_w^+ f)(u)\|_p \quad \text{and} \\ \varepsilon(f(u)) &= \partial_t f(u) = -\|(\nabla_w^- f)(u)\|_p. \end{aligned}$$

On the contrary to PDEs case, **no spatial discretization is needed** thanks to derivatives directly expressed in a discrete form. With $f^n(u) \approx f(u, n\Delta t)$, $\forall u \in V$ and at time $n+1$, we have the iterative algorithms

$$\begin{aligned} \text{dilations: } f^{n+1}(u) &= f^n(u) + \Delta t \|(\nabla_w^+ f)^n(u)\|_p \\ \text{erosions: } f^{n+1}(u) &= f^n(u) - \Delta t \|(\nabla_w^- f)^n(u)\|_p \end{aligned}$$

with $f^{n=0} = f^0$ and where $f^0 \in \mathcal{H}(V)$ is the initial function defined on the graph vertices.

Relation with other methods

With specific parameters and graphs, the proposed formulation recovers (1) the **Osher-Sethian discretization scheme** used in continuous morphology implementation and (2) the **classical algebraic flat morphological dilation and erosion**.

Levelings reformulation

[4] introduced nonlinear PDEs that model levelings. The **discrete analogue** of such continuous formulation over graphs is, $\forall u \in V$

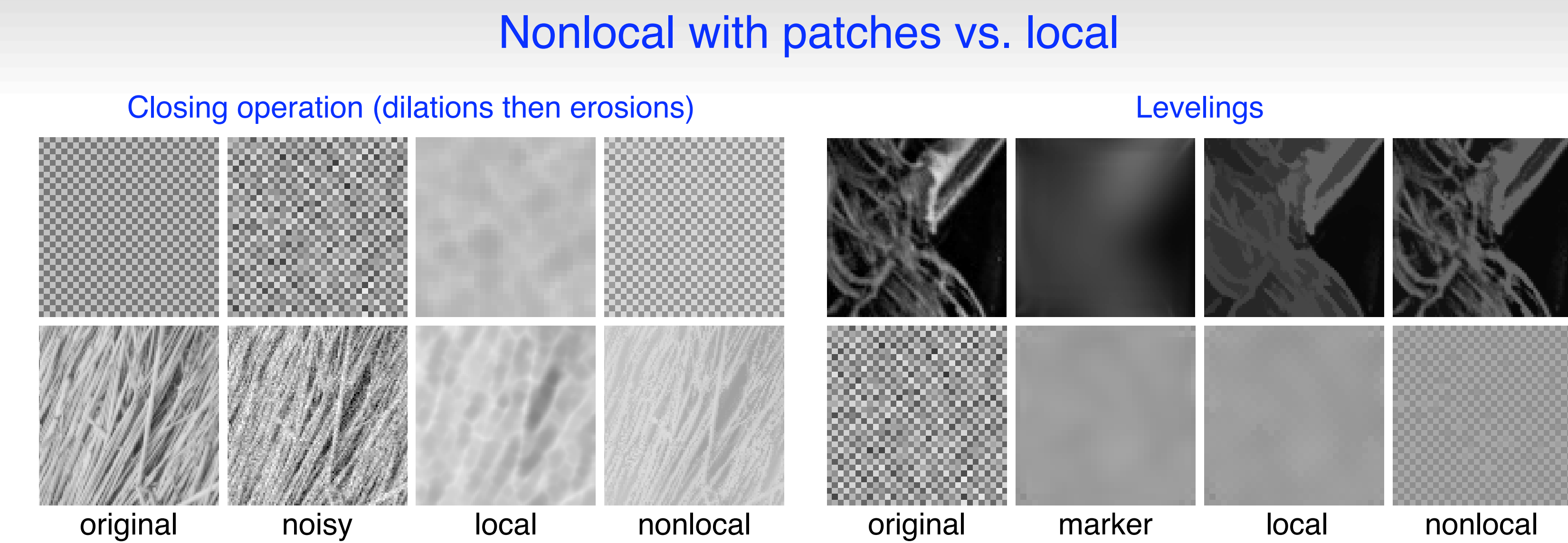
$$\partial_t f(u) = \text{sgn}(f^0(u) - f(u)) \|(\nabla_w^\pm f)(u)\|_p$$

with $f = m$ at $t=0$. $f^0 \in \mathcal{H}(V)$ is a *reference function* and $m \in \mathcal{H}(V)$ is a *marker function* from which levelings can be produced. The sign function sgn controls the evolution:

- If $f^0 > f$ then the process acts as **dilation** (with $\nabla_w^\pm = \nabla_w^+$).
- If $f^0 < f$ then the process acts as **erosion** (with $\nabla_w^\pm = \nabla_w^-$).

4 Adaptive morphology in image processing

Weighted vs. Unweighted

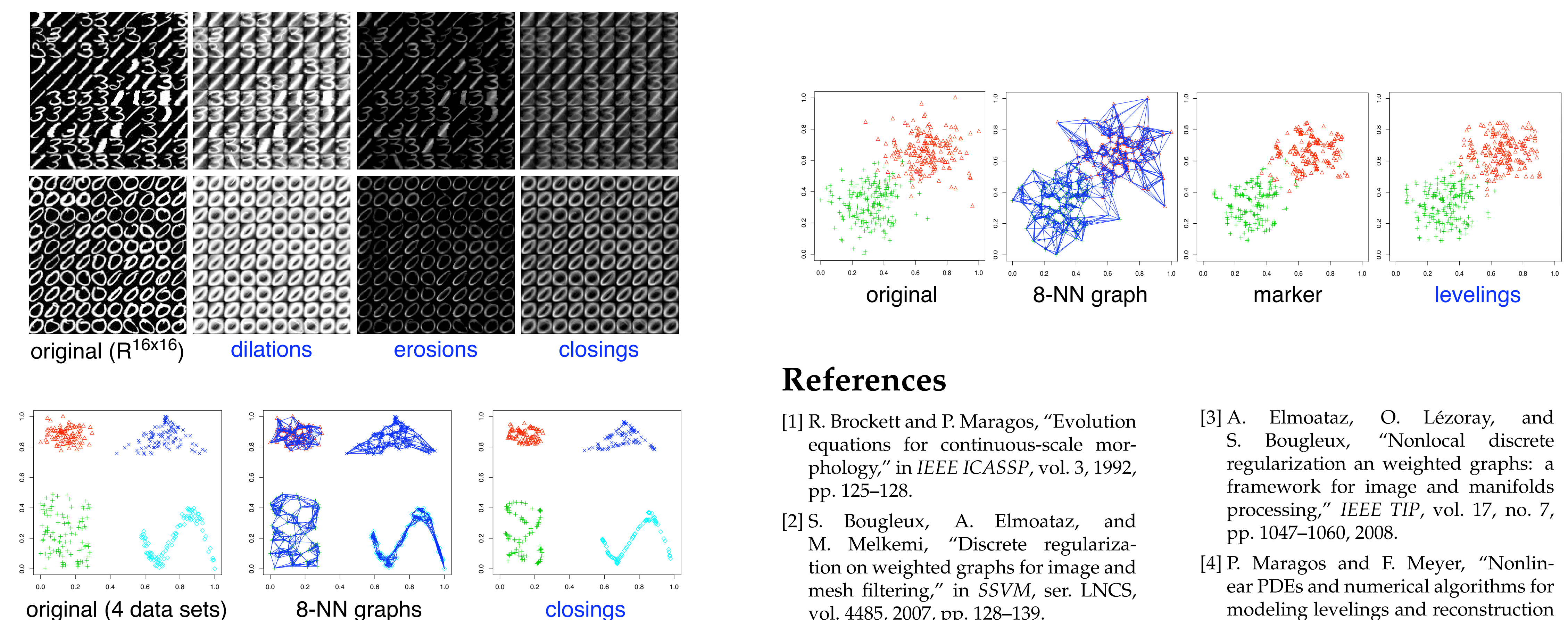


5 Extension to arbitrary graphs

Fast image processing with Region Adjacency Graph (RAG)



Morphological processing of unorganized data



References

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Contact

email: vinhthong.ta@unicaen.fr
website: www.info.unicaen.fr/~vta

